

Lect 21 Path integral for quantum mechanics

● §1 propagator of a point particle.

Consider $H = \frac{p^2}{2m} + V(x)$, and thus the time evolution operator is

$U(t_b, t_a) = e^{-i(t_b - t_a)H}$. Define the propagator

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 Schrödinger Eq as $iG(x_b, t_b; x_a, t_a) \equiv \langle x_b | U(t_b, t_a) | x_a \rangle$, then it satisfies the following

$$i\partial_t G(x, t; x_a, t_a) = \langle x | i\partial_t e^{-i(t-t_a)H} | x_a \rangle = \langle x | H U(t, t_a) | x_a \rangle$$

H in the coordinate rep is a function of x and ∂_x , thus

$$\begin{aligned} \langle x | H U(t, t_a) | x_a \rangle &= \int dx' \delta(x-x') H(x', \partial_{x'}) U(t, t_a) \delta(x'-x_a) \\ &= H(x, \partial_x) \int dx' \delta(x-x') U(t, t_a) \delta(x'-x_a) = H(x, \partial_x) \langle x | U(t, t_a) | x_a \rangle \end{aligned}$$

$$\Rightarrow i\partial_t G(x, t; x_a, t_a) = H(x, \partial_x) G(x, t; x_a, t_a)$$

Ex: for 1D free space, with the initial condition $G(x, t_a; x_a, t_a) = -i\delta(x-x_a)$,

we have $G(x_b, t; x_a, t_a) = (-i) \left(\frac{m}{2\pi i t}\right)^{1/2} \exp\left[\frac{i m (x_b - x_a)^2}{2t}\right]$.

Hint: Solve the differential Eq. $i\partial_t G(x, t; x_a, t_a) = -\frac{\hbar^2}{2m} \partial_x^2 G(x, t; x_a, t_a)$.

● §2 Path integral representations of the propagator

$$U(t_b, t_a) = U(t_b, t) U(t, t_a) \Rightarrow iG(x_b, t_b; x_a, t_a) = \int dx iG(x_b, t_b; x, t) iG(x, t; x_a, t_a)$$

let us divide the time interval $[t_b, t_a]$ into N equal segments

$$iG(x_b, t_b; x_a, t_a) = \int dx_1 \dots dx_{N-1} iG(x_b, t_b; x_{N-1}, t_{N-1}) \dots iG(x_1, t_1; x_a, t_a)$$

$$= A^N \int \prod_{i=1}^{N-1} dx_i \exp\left[i \sum_{j=1}^N \Delta t L\left(t_j, \frac{x_j + x_{j-1}}{2}, \frac{x_j - x_{j-1}}{\Delta t}\right)\right]$$

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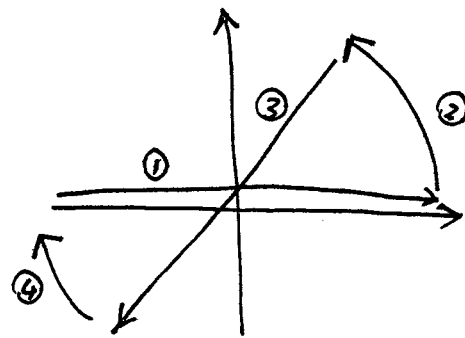
$$iG(x_i, t_i; x_{i-1}, t_{i-1}) = \langle x_i | e^{-\frac{i p^2}{2m} \Delta t} e^{-iV(x)\Delta t} | x_{i-1} \rangle$$

$$= \int dp_i \langle x_i | e^{-\frac{i p^2}{2m} \Delta t} | p_i \rangle \langle p_i | e^{-iV(x)\Delta t} | x_{i-1} \rangle$$

$$= \int_{-\infty}^{+\infty} \frac{dp_i}{2\pi} e^{-\frac{i p_i^2}{2m} \Delta t - iV(x)\Delta t} e^{+i p_i (x_i - x_{i-1})}$$

using Gauss integral $\int_{-\infty}^{+\infty} dx e^{-ax^2} = \sqrt{\frac{\pi}{a}}$

then what's the value of $\int_{-\infty}^{+\infty} dx e^{-iax^2} = ?$



For the contour $\oint e^{-az^2} dz = \int_1 + \int_2 + \int_3 + \int_4 = 0$, the contribution from 2 and 4 $\rightarrow 0$

$$\int_{-\infty}^{+\infty} dx e^{-ax^2} = \int_{-\infty}^{+\infty} dz e^{-az^2} = \int_{-\infty}^{+\infty} dy e^{-ia|y|^2} \cdot e^{i\pi/4}$$

$$\Rightarrow \int_{-\infty}^{+\infty} dy e^{-ia|y|^2} = e^{-i\pi/4} \sqrt{\frac{\pi}{a}} = \sqrt{\frac{\pi}{ai}}$$

$$\Rightarrow iG(x_i, t_i; x_{i-1}, t_{i-1}) = \left(\frac{m}{2\pi i \Delta t}\right)^{1/2} \exp\left[i\left(\frac{m}{2} \frac{(x_i - x_{i-1})^2}{(\Delta t)^2} - V\left(\frac{x_i + x_{i-1}}{2}\right)\right)\Delta t\right]$$

$$\Rightarrow A = \left(\frac{m}{2\pi i \hbar \Delta t}\right)^{1/2} \text{ and } L(t, x, \dot{x}) = \frac{m}{2} \dot{x}^2 - V(x)$$

i.e.

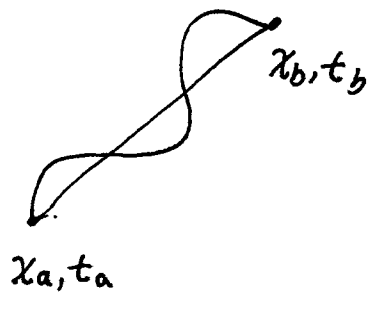
$$iG(x_b, t_b, x_a, t_a) = \left(\frac{m}{2\pi i \hbar \Delta t}\right)^{N/2} \int dx_1 \dots dx_{N-1} e^{i \int_{t_a}^{t_b} dt \left(\frac{m}{2} \dot{x}^2 - V(x)\right)}$$

§ Evaluation of the path integral:

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 We can first find the saddle point solution, which corresponds to the solution of the classic path, and then evaluate the fluctuation parts. Let us consider the free space propagator as an example.

The classic path

$$X_c(t) = X_a + \frac{X_b - X_a}{t_b - t_a} (t - t_a)$$



The action of this part $\int_{t_a}^{t_b} L dt$

$$= \frac{m}{2} \dot{x}^2 (t_b - t_a) = \frac{m}{2} \frac{(X_b - X_a)^2}{t_b - t_a}$$

The fluctuations $\delta X_j = X_j - X_c(t_j)$, $\begin{cases} X_0 = X_a & \delta X_0 = \delta X_N = 0 \\ X_N = X_b \end{cases}$

$$iG(x_b, t_b; x_a, t_a) = \left(\frac{m}{2\pi i \hbar \Delta t}\right)^{N/2} \int dx_1 \dots dx_{N-1} \prod_{i=1}^N \exp\left[i \frac{m}{2} \frac{(X_i - X_{i-1})^2}{\Delta t}\right]$$

$$\frac{(X_i - X_{i-1})^2}{\Delta t} = \frac{(X_c(t_i) - X_c(t_{i-1}))^2}{\Delta t} + 2(\delta X_i - \delta X_{i-1}) \frac{X_b - X_a}{t_b - t_a}$$

Add together, the linear term of δX_i vanishes,

$$\Rightarrow iG(x_b, t_b; x_a, t_a) = \left(\frac{m}{2\pi i \Delta t}\right)^{N/2} e^{iS_c} \int dx_1 \dots dx_{N-1} \prod_{i=2}^{N-1} e^{i \frac{m}{2} \frac{(\delta X_i - \delta X_{i-1})^2}{\Delta t}} \cdot e^{i \frac{m}{2} [(\delta X_1)^2 + (\delta X_{N-1})^2]}$$

$$\cdot \exp\left[i \sum_{j,k} \delta X_j M_{jk} \delta X_k\right]$$

with $M_{jk} = \frac{m}{2\Delta t} \begin{bmatrix} 2 & -1 & & & \\ -1 & 2 & -1 & & \\ & & \ddots & \ddots & \\ & & & & -1 & 2 \end{bmatrix}$

$$\int dx_1 \dots dx_{N-1} \exp\left[i \sum_{j,k} \delta X_j M_{jk} \delta X_k\right] = \frac{(\sqrt{\pi})^{N-1}}{\sqrt{\text{Det}(-iM)}} \quad (\text{gaussian fluctuations})$$

tricks to calculate determinant of $M_N = \begin{pmatrix} 2\cosh(u) & -1 & & \\ -1 & 2\cosh(u) & -1 & \\ & & \ddots & \\ -1 & & & 2\cosh(u) \end{pmatrix}$

$$\text{Det } M_N = 2\cosh(u) \text{Det } M_{N-1} - \text{Det } M_{N-2}$$

$$\text{Det } M_1 = 2\cosh(u), \quad \text{Det } M_2 = 4\cosh^2(u) - 1$$

can be solved by the ansatz $\text{Det } M_N = a e^{nu} + b e^{-nu}$

$$\Rightarrow \text{Det } M_N = \frac{\sinh(N+1)u}{\sinh u} \rightarrow N+1 \text{ as } u \rightarrow 0$$

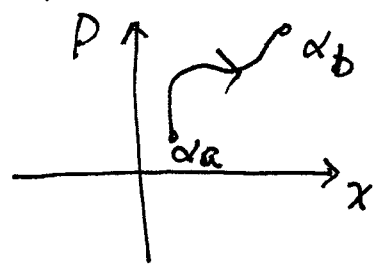
$$\Rightarrow \text{Det}(-iM_{jk}) = \left(\frac{m}{2\Delta t i}\right)^{N-1} N!$$

$$\Rightarrow iG(x_b, t_b; x_a, t_a) = \left(\frac{m}{2\pi i \Delta t}\right)^{N/2} \left(\frac{m}{2\pi i \Delta t}\right)^{-\frac{(N-1)}{2}} N^{-1/2} e^{iS_c}$$

$$iG(x_b, t_b; x_a, t_a) = \left(\frac{m}{2\pi i (t_b - t_a)}\right)^{1/2} e^{iS_c}$$

§ Coherent state path integral

Consider a harmonic oscillator $H = \omega a^\dagger a$, and we define the coherent state $|\alpha\rangle$ satisfying $a|\alpha\rangle = \alpha|\alpha\rangle$. The propagator in the coherent state rep is even simpler.



$$iG(\alpha_b t_b; \alpha_a t_a) = \langle \alpha_b | U(t_b t_a) | \alpha_a \rangle$$

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Resolution identity

$$\int \frac{d\text{Re}\alpha d\text{Im}\alpha}{\pi} |\alpha\rangle \langle \alpha| = 1$$

Plug in

$$|\alpha\rangle = e^{-\frac{|\alpha|^2}{2}} \sum_{n=0}^{\infty} \frac{\alpha^n}{\sqrt{n!}} |n\rangle$$

$$= N_\alpha e^{\alpha a^\dagger} |0\rangle$$

Proof: LHS = $\int \frac{d\text{Re}\alpha d\text{Im}\alpha}{\pi} e^{-|\alpha|^2} \sum_{nn'} \frac{\alpha^n \alpha'^{n'}}{\sqrt{n!n'!}} |n\rangle \langle n'|$

= $\int \frac{d\theta}{\pi} |\alpha| d|\alpha| e^{-|\alpha|^2} \sum_n \frac{|\alpha|^{2n}}{n!} |n\rangle \langle n|$ ← For those $n \neq n'$, they vanish after $\int d\theta$

= $\sum_n \int_0^\infty d|\alpha|^2 \frac{e^{-|\alpha|^2} (|\alpha|^2)^n}{n!} |n\rangle \langle n| = \sum_n |n\rangle \langle n| = 1$

Γ-function

Inner product

$$\langle \alpha | \alpha' \rangle = e^{-\frac{|\alpha|^2}{2}} e^{-\frac{|\alpha'|^2}{2}} \langle 0 | e^{\alpha^* \hat{a}} e^{\alpha' \hat{a}^\dagger} | 0 \rangle$$

$$e^{\alpha^* \hat{a}} e^{\alpha' \hat{a}^\dagger} = e^{\alpha' \hat{a}^\dagger} e^{\alpha^* \hat{a}} e^{\alpha^* \alpha' [\hat{a}, \hat{a}^\dagger]}$$

$$\Rightarrow \langle \alpha | \alpha' \rangle = e^{-\frac{1}{2}(|\alpha|^2 + |\alpha'|^2) + \alpha^* \alpha'}$$

$$iG(\alpha_b t_b; \alpha_a t_a) = \int \frac{d\alpha_1 \dots d\alpha_{N-1}}{\pi^{N-1}} iG(\alpha_b t_b, \alpha_{N-1} t_{N-1}) \dots iG(\alpha_1 t_1; \alpha_a t_a)$$

$$iG(\alpha_i t_i, \alpha_{i-1} t_{i-1}) = \langle \alpha_i | e^{-i\omega t \hat{a}^\dagger \hat{a}} | \alpha_{i-1} \rangle = e^{-i\omega t \alpha_i^* \alpha_{i-1}} \langle \alpha_i | \alpha_{i-1} \rangle$$

$$= e^{-i\omega t \alpha_i^* \alpha_{i-1}} - \frac{1}{2} |\alpha_i|^2 - \frac{1}{2} |\alpha_{i-1}|^2 + \alpha_i^* \alpha_{i-1}$$

$$= e^{-i\omega t \alpha_i^* \alpha_{i-1}} - \frac{1}{2} \alpha_i^* (\alpha_i - \alpha_{i-1}) + \frac{1}{2} \alpha_{i-1} (-\alpha_{i-1} + \alpha_i^*)$$

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$$= e^{i\omega t} [-\omega \alpha_i^* \alpha_i + \frac{i}{2} (\alpha_i^* \dot{\alpha}_i - \dot{\alpha}_i \alpha_i^*)]$$

$$\Rightarrow iG(\alpha_b t_b; \alpha_a t_a) = \int \frac{\prod_{i=1}^{N-1} d\alpha_i}{\pi^{N-1}} e^{i \int_{t_a}^{t_b} dt [\frac{i}{2} (\alpha^* \dot{\alpha} - \dot{\alpha} \alpha^*) - \omega \alpha^* \alpha]}$$

$$\rightarrow \int D[\alpha(t)] e^{i \int_{t_a}^{t_b} dt \mathcal{L}}$$

where $\mathcal{L} = \frac{i}{2} (\alpha^* \dot{\alpha} - \dot{\alpha} \alpha^*) - \omega \alpha^* \alpha = p \dot{x} - H$.

§ Path integral Rep of partition function

$$Z(\beta) = \text{tr} e^{-\beta H} = \int dx \mathcal{y}(x, x, \beta) \text{ where } \beta = \frac{1}{k_B T}$$

$$\mathcal{y}(x_b, x_a; \beta) \equiv \langle x_b | e^{-\beta H} | x_a \rangle$$

$$= \left(\frac{m}{2\pi\hbar\beta}\right)^{N/2} \int D\chi(z) e^{-\int_0^\beta dz \left[\frac{m}{2} \left(\frac{d\chi}{dz}\right)^2 + V(\chi)\right]}$$

$$\Rightarrow Z(\beta) = \int D\chi(z) e^{-\oint dz \left[\frac{m}{2} \left(\frac{d\chi}{dz}\right)^2 + V(\chi)\right]} \text{ for closed path } \chi(0) = \chi(\beta).$$

$$y(x_b, x_a, z) \Big|_{z=it} = i G(x_b, x_a; t)$$

imaginary time path integral

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