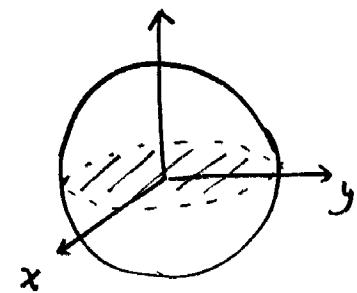


Lect 12 Conservation laws (II)

①

§ conservation of momentum

example: the net force on the "northern" hemisphere of a uniformly charged solid sphere of radius R and charge Q .



Solution: method ① using the stress tensor

$$T_{ij} = \frac{1}{4\pi} (E_i E_j - \frac{1}{2} \delta_{ij} E^2) + \frac{1}{4\pi} (B_i B_j - \frac{1}{2} \delta_{ij} B^2)$$

$$f_i = \nabla_j T_{ji} . \quad \text{in our case } B=0, \Rightarrow \vec{S}=0$$

and T_{ij} only contains
E-field.

$$- \frac{1}{c^2} \frac{\partial}{\partial t} \vec{S}$$

$$\Rightarrow f_i = \frac{1}{4\pi} \nabla_j (E_i E_j - \frac{1}{2} \delta_{ij} E^2) \Rightarrow F_i = \frac{1}{4\pi} \oint_s (E_j E_i - \frac{1}{2} \delta_{ij} E^2) dA_j$$

The boundary surface consists of two parts — a hemisphere "bowl" at radius R and a circular disk of the cross section at xy plane.

① total force on the bowl

$$dA = R^2 \sin\theta d\theta d\phi \hat{r}, \quad E = \frac{Q}{R^2} \hat{r}$$

$$\hat{r} = \sin\theta \cos\phi \hat{x} + \sin\theta \sin\phi \hat{y} + \cos\theta \hat{z}$$

The total force is along the z-axis due to the rotational sym
along the z-axis

(2)

$$T_{xz} = \frac{1}{4\pi} E_x E_z = \frac{Q^2}{4\pi R^4} \sin\theta \cos\theta \cos\phi$$

$$T_{yz} = \frac{1}{4\pi} E_y E_z = \frac{Q^2}{4\pi R^4} \sin\theta \cos\theta \sin\phi$$

$$T_{zz} = \frac{1}{8\pi} [E_z^2 - E_x^2 - E_y^2] = \frac{1}{8\pi} \left[\frac{Q^2}{R^4} \right] [\cos^2\theta - \sin^2\theta] = \frac{Q^2}{8\pi R^4} \cos 2\theta$$

$$\Rightarrow dF_z = T_{xz} d\alpha_x + T_{yz} d\alpha_y + T_{zz} d\alpha_z$$

$$= \frac{Q^2}{4\pi R^4} R^2 \left[\underbrace{\sin\theta \cos\theta \cos\phi \sin^2\theta \cos\phi + \sin\theta \cos\theta \sin\phi \sin^2\theta \sin\phi}_{+ \frac{1}{2} \cos 2\theta \sin\theta \cos\theta} \right] d\theta d\phi$$

$$= \frac{\sin\theta \cos\theta}{2} \cdot \frac{Q^2}{4\pi R^2} d\theta d\phi \quad \xrightarrow{\text{add together}} \frac{1}{2} \sin\theta \cos\theta$$

$$\Rightarrow F_{\text{bowl}} = \frac{Q^2}{8\pi R^2} \int_0^{\frac{\pi}{2}} \sin\theta \cos\theta d\theta \int_0^{2\pi} d\phi = \frac{Q^2 \cdot 2\pi}{8\pi R^2} \left(-\frac{1}{4} \cos 2\theta \right) \Big|_0^{\frac{\pi}{2}} = \frac{Q^2}{8 R^2}$$

② total force on the disk: $d\vec{a} = -r dr d\phi \hat{z}$

$$E = \frac{Q}{R^3} \vec{r} = \frac{Q}{R^3} r [\cos\phi \hat{x} + \sin\phi \hat{y}]$$

$$T_{xz} = T_{yz} = 0, \quad T_{zz} = \frac{-1}{8\pi} (E_x^2 + E_y^2) = \frac{-1}{8\pi} \frac{Q^2}{R^6} r^2$$

$$dF_z = T_{zz} d\alpha_z = \frac{1}{8\pi} \frac{Q^2}{R^6} r^3 dr d\phi \Rightarrow F_{\text{disk}} = \frac{2\pi}{8\pi} \frac{Q^2}{R^6} \frac{R^4}{4}$$

$$\Rightarrow \text{total force} \quad \boxed{\frac{3Q^2}{16R^2} = F_{\text{bowl}} + F_{\text{disk}}} \quad = \frac{Q^2}{16R^2}$$

method ②: we choose the infinitely large plane xy , which encloses the upper hemisphere. For $r < R$, we have already got $F = \frac{Q^2}{16R^2}$.

$$\text{For } +\infty > r > R, \quad E = \frac{Q}{r^2} (\cos\phi \hat{x} + \sin\phi \hat{y})$$

$$T_{xz} = T_{yz} = 0, \quad T_{zz} = -\frac{(E_x^2 + E_y^2)}{8\pi} = -\frac{1}{8\pi} \frac{Q^2}{r^4}$$

$$dF_{zz} = T_{zz} dA_z = \frac{1}{8\pi} \frac{Q^2}{r^4} r dr d\phi = \frac{Q^2}{8\pi r^3} dr d\phi$$

$$\Rightarrow F_z = \frac{Q^2}{8\pi} \cdot 2\pi \int_R^\infty \frac{dr}{r^3} = \frac{Q^2}{4} \frac{1}{2R^2} = \frac{Q^2}{8R^2}$$

$$\left. \begin{aligned} &\text{add together} \\ &F = \frac{Q^2}{16R^2} + \frac{Q^2}{8R^2} \\ &= \frac{3Q^2}{16R^2} \end{aligned} \right\}$$

method ③ inside bulk

$$\vec{E} = \frac{1}{r^2} Q \left(\frac{r}{R}\right)^3 \hat{r} = \frac{r}{R^3} Q \hat{r}$$

$$d\vec{F} = \rho \vec{E} dr, \quad \rho = \frac{Q}{\frac{4\pi}{3} R^3}$$

$$dF_z = \frac{Q}{\frac{4\pi}{3} R^3} \cdot \frac{r}{R^3} Q \cos\theta \cdot \underbrace{r^2 \sin\theta d\theta d\phi}_{dr}$$

$$\begin{aligned} \Rightarrow F_z, \text{upper hemi;} &= \int d\vec{F}_z = \frac{Q^2}{\frac{4\pi}{3} R^6} \int_0^R r^3 dr \int_0^{2\pi} d\varphi \int_0^{\frac{\pi}{2}} \sin\theta d\theta \\ &= \frac{3Q^2}{4\pi R^6} \cdot \frac{R^4}{4} \cdot 2\pi \cdot \frac{1}{2} = \frac{3}{16} \frac{Q^2}{R^2} \end{aligned}$$

Angular momentum of E & M field

The energy stored in the E & M field $U_{em} = \frac{1}{8\pi} E^2 + \frac{1}{8\pi} B^2$.

momentum $\vec{P}_{em} = \frac{1}{4\pi c} \vec{E} \times \vec{B}$.

we can define the angular momentum density

$$\vec{\ell}_{em} = \vec{r} \times \vec{P}_{em} = \frac{1}{4\pi c} \vec{r} \times (\vec{E} \times \vec{B}).$$

from

$$f_i = \nabla_j T_{ji} - \frac{1}{c^2} \frac{\partial}{\partial t} S_i$$

$$\tau_i = \epsilon_{ijk} T_j f_k = \epsilon_{ijk} r_j \nabla_t T_{tk} - \frac{1}{c^2} \frac{\partial}{\partial t} \epsilon_{ijk} r_j S_k$$

$$\begin{aligned} \text{define } M_{ij} &= T_{ie} r_k \epsilon_{jek} \Rightarrow \nabla_i M_{ij} = \nabla_i (T_{ie} r_k) \epsilon_{jek} \\ &= (\nabla_i T_{ie}) r_k \epsilon_{jek} + T_{ie} \delta_{ik} \epsilon_{jek} \end{aligned}$$

$$\Rightarrow \cancel{\nabla_j M_{ji}} = \cancel{\epsilon_{ijk} \epsilon_{jek} \nabla_t T_{jt}} \quad T_{ke} \epsilon_{jek} = 0$$

$$\Rightarrow \tau_i = \nabla_j M_{ji} - \frac{1}{c^2} \frac{\partial}{\partial t} l_i \quad \text{where } l_i = \epsilon_{ijk} r_j S_k$$

$$\Rightarrow \boxed{\frac{d}{dt} \iiint d^3 r \ l_i + \oint (-M_{ji} da_j) = - \iiint d^3 r \ \tau_i}$$

Example 8.4 Page 359.

- a very long solenoid with radius R , n turns per unit length, and current I . Inside and outside are two charged shells with $\pm Q$, respectively.

cylindrical

When current in the solenoid turn off gradually, we know the cylinders begin to rotate. How the angular momentum comes from?

Solution ① The B -field inside the solenoid induced by changing I is

$$B \cdot l = \frac{4\pi}{c} NI \Rightarrow B = \frac{4\pi n}{c} I,$$

$$E_i \cdot 2\pi r = - \frac{1}{c} \frac{\partial}{\partial t} (B \cdot \pi R^2) = - \frac{n}{c^2} 4\pi^2 R^2 \frac{\partial I}{\partial t}$$

$$E_i = - \frac{2\pi R^2 n}{c r} \frac{\partial I}{\partial t} \hat{z} \quad \text{for } r > R,$$

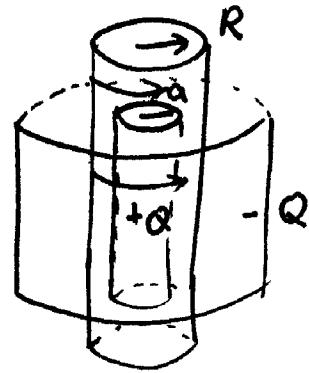
$$E_i \cdot 2\pi r = - \frac{1}{c} \frac{\partial}{\partial t} B \cdot \pi r^2 = - \frac{n}{c^2} 4\pi^2 r^2 \frac{\partial I}{\partial t}$$

$$E_i = - \frac{2\pi r n}{c^2} \frac{\partial I}{\partial t} \hat{z} \quad \text{for } r < R.$$

E_i is along the tangential direction \Rightarrow The torque on the outer

cylinder is $-b \cdot Q E = - \frac{2\pi R^2 n Q}{c^2 b} \cdot b \frac{\partial I}{\partial t}$

$$\Rightarrow I_b = + \int T dt = - \frac{2\pi R^2 n Q}{c^2} I \hat{z}$$



the torque on the inner cylinder $aQE = -\frac{2\pi a^2}{c^2} n \frac{\partial I}{\partial t} \hat{z}$

$$L_a = \frac{2\pi a^2}{c^2} n Q I \hat{z}$$

\Rightarrow the mechanical angular momenta together $L_a + L_b = -\frac{2\pi}{c^2} n Q I (R^2 - a^2)$

now let us check the angular momentum density from the field.

$\vec{E} = \frac{2Q}{\ell r} \hat{e}_r$ for $a < r < b$, (by using Gauss' law).

B field only lies inside the solenoid at $r < R$, in which

$$\vec{B} = \frac{4\pi n}{c} I \hat{e}_z$$

$$\Rightarrow \vec{P}_{em} = \frac{\vec{E} \times \vec{B}}{4\pi c} = \frac{1}{4\pi c} \cdot \frac{2Q}{\ell r} \cdot \frac{4\pi n}{c} I \hat{e}_r \times \hat{e}_z = \frac{2nQI}{c^2 \ell r} (-\hat{e}_\theta)$$

$$\vec{l}_{em} = \vec{r} \times \vec{P}_{em} = r \hat{e}_r \times \frac{2nQI}{c^2 \ell r} (-\hat{e}_\theta) = -\frac{2nQI}{c^2 \ell} \hat{e}_z$$

$$\Rightarrow \vec{L}_{em} = \int_a^R l_{em} 2\pi r dr = -\frac{2nQI}{c^2 \ell} \pi (R^2 - a^2)$$

This amount of angular momentum is transferred to

mechanical angular momentum.