

## Physics 120B: Lecture 7

Sensors  
(bit incomplete, still)

### Sensing Categories

- Voltage
  - starting easy: analog in
- Distance
  - acoustic or light
- Speed
  - hard; usu. via distance
- Acceleration
  - accelerometers
- Light Level
  - phototransistors, photodiodes
- Object Passage
  - photogate (light source/sense)
- Sound Level
  - microphone to rectifier?
- Temperature
  - RTD, thermistor, AD-590
- Magnetic Flux
  - coil and EMF
- Pressure
  - pads?
- Mass
  - spring stretch?
- Strain
  - strain gauge

[http://en.wikipedia.org/wiki/List\\_of\\_sensors](http://en.wikipedia.org/wiki/List_of_sensors) for overwhelming list

## Voltage

- Crudest version is digital: HIGH or LOW: **1-bit** resolution
  - lots of digital inputs to handle this
  - option for internal pull-up resistor to  $V_{CC}$
- Analog in provides **10-bit** (0–1023) on Arduino
  - considered on crude-to-modest side: 50 mV in 5 V
  - high-end is **16-bit** (65536 values)
    - seldom meaningful to carry more precision than this
  - **12-bit** is also common, and 4× improvement over 10-bit
  - **8-bit** is painful: 0.2 V in 5 V
    - but fine for some applications
- Voltage is seldom what you fundamentally want to know, but is often the electronic analog of a physical quantity of greater interest
  - generally, “converter” can be termed *transducer*

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## Distance

- Popular 120B metric
  - collision avoidance; parallel park; target approach
- Acoustic variety
  - ultrasound burst and time-of-flight measurement
  - Parallax Ping unit is integrated unit, \$30
    - 2 cm to 3 m (dep. on surface type)
  - must send 2  $\mu$ s pulse on SIG pin
  - then listen for return pulse
    - duration of pulse is round-trip time
  - must switch same pin between input/output
  - use `pulseIn()` to measure input duration
- Other modules in lab to roll your own acoustic sensor

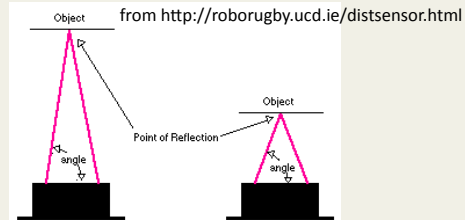


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## Distance via Light?

- Not time-of-flight; forget about it! Leave that to pros
- Clever sensing of angle between emitter and receiver



- Detector is linear array behind lens
  - angle maps to position, indicating distance
- Smarts on board, so GND, +5 V in; analog voltage out proportional to distance, though not linearly so
- Also a proximity version: logic out dep. on “too close”

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## Measure Speed?

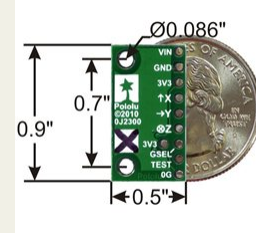
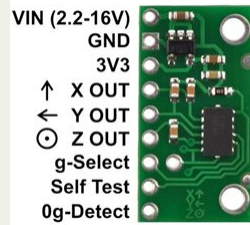
- Galileo and Einstein would both agree that this is hard to directly sense
- Options
  - measure distance and rate of change
    - noise in distance measurement can make for ratty/spiky velocity
  - Doppler?
  - measure rotation rate of wheel or axle engaged in motion
    - what speedometers do
    - can use photogate for once/revolution knowledge

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## Acceleration

- This is something we *can* directly sense
- Recent rapid advances; driven by MEMs and smartphones
  - 3-axis accelerometer based on micro-cantilevers capacitively sensed
  - bitty MMA7361L unit, \$15
    - centers output on  $\frac{1}{2}$  of 3.3 V
    - default roughly  $\pm 1.5g$ , but can config. for  $\pm 6g$
    - zero-g detection and digital flag

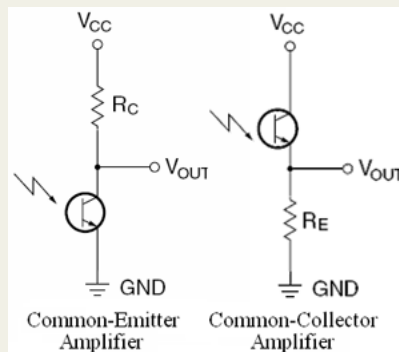


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## Light Level

- Lots of options: phototransistor, photodiode most common
  - photons knock electrons loose, which either constitute a base current (phototransistor) or direct into current (photodiode)
- Phototransistor (right) effectively has some gain already
  - 10 k $\Omega$  usually about right

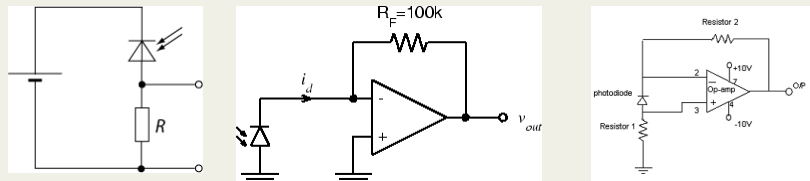


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## Photodiode Read Out

- Many options for photodiode
  - reverse bias, developing voltage across resistor
  - zero bias, in op-amp feedback mode

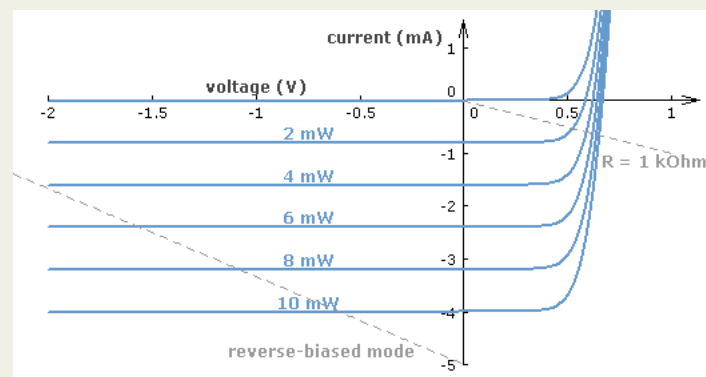


- Typically < 0.4 A per Watt incident
  - stream of photons at 550 nm  $\rightarrow$  0.447 A at 100% Q.E.
  - so 1 mm<sup>2</sup> detector in full sun (1000 W/m<sup>2</sup>) is 1 mW
  - thus at best 0.5 mA current (puny)
  - tend to want pretty large resistor to build up voltage

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## Photodiode IV Curve



- At zero or reverse bias, current is proportional to incident light power
  - note approximate relation:  $I \approx 0.4P$
  - matches quantum expectations

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## Object Passage

- We often need to know if something is physically present, has passed through, count rotations, etc.
- Can have simple scheme of light source and light detector, where the something of interest passes between
  - termed a *photogate*
  - interruption of light level pretty unmistakably sensed
  - pulse duration, via `pulseIn()`, may even speak to velocity
- Magnetic

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## Temperature

- Exploit temperature dependence of materials
  - RTD: resistive temperature device
    - usually laser-etched platinum spiral, often  $1000 \Omega + 3.85 \times (T - 0^\circ\text{C}) \Omega$
    - linear, good absolute calibration
    - but a resistor: need to fashion accurate current source and read off voltage (make ohmmeter)
  - thermistor: exploits conduction electron density as  $e^T$ 
    - nonlinear, due to exponential dependence on T
  - AD-590: Analog Devices
    - supply 5 V and a route for current (resistor), and output current is proportional to temperature
    - measure current as voltage across provided resistor
- Caution: resistors often 200 ppm per  $^\circ\text{C}$ 
  - for accuracy, may want low “tempco” resistors

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## Sound Level

- Microphone is transducer for acoustic vibrations into voltage
  - usually membrane that vibrates is part of capacitor
  - can rectify resulting waveform, low-pass, and measure level

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## Magnetic Flux

- A loop of wire (or many loops) will develop EMF according to changing magnetic field
  - can amplify, rectify, etc.
- A Hall sensor can measure DC magnetic field

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## Pressure

- Pressure pads: 2 conductors separated by carbon film, squeezes out; so more conductivity: bite pads
- Capacitive pressure deflects membrane (lab pressure meter)
- Party-roller paper tube

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## Mass/Weight

- “Spring” stretch plus flexometer (strain gauge)

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## Strain

- Strain gauge can tell you about minute flexing of a structural beam/material

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## Other Sensors

- Direction
  - HM55B Compass Module from Parallax (\$30)
- Motion
  - infrared motion sensor

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