

lect 4 Quadratic air resistance / magnetic cyclotron

$$m\dot{\vec{v}} = m\vec{g} - c v^2 \hat{v} = m\vec{g} - c \sqrt{v_x^2 + v_y^2} \vec{v}, \text{ where } c = \gamma D^2$$

$$\Rightarrow \begin{cases} m\dot{v}_x = -c \sqrt{v_x^2 + v_y^2} v_x \\ m\dot{v}_y = mg - c \sqrt{v_x^2 + v_y^2} v_y \end{cases} \quad \begin{array}{l} \text{the motions along } x \text{ and } y \\ \text{directions couple} \end{array}$$

We first solve two special cases

① no gravity, a body only moves along x-direction.
(or gravity is balanced)

By setting $v_y = 0$, we have $m\dot{v}_x = -c v_x^2$

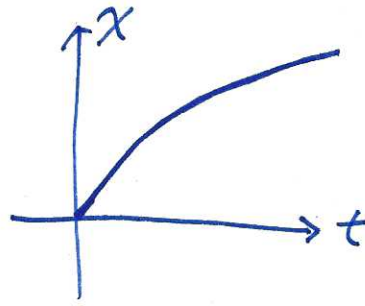
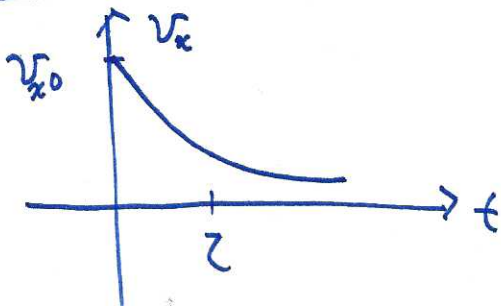
$$\Rightarrow m \frac{dv_x}{v_x^2} = -c dt \Rightarrow m \int_{v_{x0}}^{v_x(t)} \frac{dv_x}{v_x^2} = -c \int_0^t dt'$$

$$m \left(\frac{1}{v_x} - \frac{1}{v_{x0}} \right) = -ct \Rightarrow \boxed{v_x(t) = \frac{v_{x0}}{1 + c v_{x0} t / m} = \frac{v_{x0}}{1 + t/\tau}}$$

where the time constant $\tau = \frac{m}{c v_{x0}}$

$$x(t) = x_0 + \int_0^t v_x(t') dt' = v_{x0} \tau \ln(1 + t/\tau)$$

by setting $x_0 = 0$



Compare with the linear drag, the decay of v_x is slower. It's powerlaw instead of exponential. Seemingly, x diverges logarithmically. But it cannot be realistic. When v is sufficiently small, the drag will become linear.

② vertical motion with $v_x = 0$. fall motion, set down as positive y-direction.

$$\dot{v}_y = g - \frac{c}{m} v_y^2$$

Again we solve the terminal velocity

$$v(\infty) = \sqrt{\frac{mg}{c}}$$

then the equation of motion $\Rightarrow \dot{v}_y = g \left(1 - \frac{v_y^2}{v(\infty)^2}\right)$

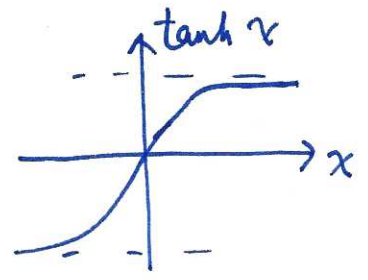
$$\Rightarrow \frac{dv_y}{1 - \frac{v_y^2}{v(\infty)^2}} = g dt \quad \Rightarrow \int_{v_{y,0}}^{v_y} \frac{dv_y}{1 - v_y^2/v(\infty)^2} = gt$$

$$\Rightarrow \frac{v(\infty)}{g} \operatorname{arctanh}\left(\frac{v_y}{v(\infty)}\right) = t. \text{ If } v_{y,0} = 0, \text{ we have}$$

$$\operatorname{arctanh}\left(\frac{v_y}{v(\infty)}\right) = \frac{gt}{v(\infty)}$$

$$\Rightarrow v_y(t) = v(\infty) \tanh \frac{gt}{v(\infty)}$$

$$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}} \approx \begin{cases} x & x \rightarrow 0 \\ 1 & x \rightarrow \infty \end{cases}$$



$$\Rightarrow y = \int_0^t dt v_y(t) = \frac{v(\infty)^2}{g} \ln \left[\cosh \frac{gt}{v(\infty)} \right]$$

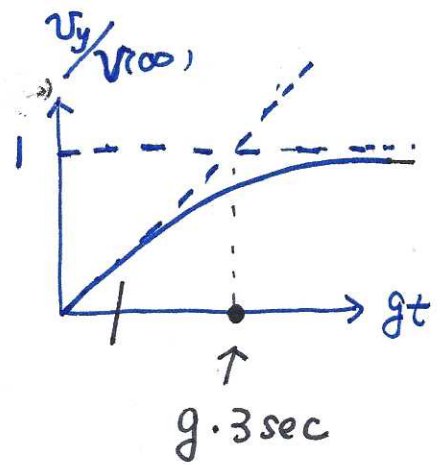
$$\cosh x = \frac{e^x + e^{-x}}{2}$$

Example: baseball $m = 0.15 \text{ kg}$, $D = 7 \text{ cm}$. $\gamma = 0.25 \text{ N s}^2/\text{m}^4$.

When it falls vertically, $v(\infty) = \sqrt{\frac{mg}{\gamma D^2}} = 35 \text{ m/s}$.
it's terminal velocity

$$v_y(t) = v(\infty) \tanh\left(\frac{gt}{v(\infty)}\right)$$

$$\approx \begin{cases} gt & \text{at } \frac{gt}{v(\infty)} \ll 1 \\ v(\infty) & \text{at } \frac{gt}{v(\infty)} \gg 1 \end{cases}$$

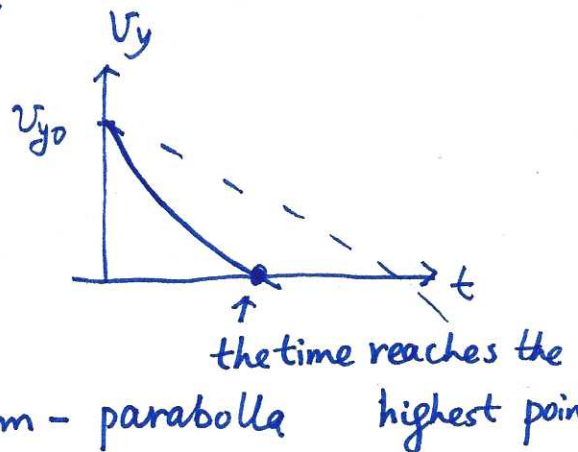
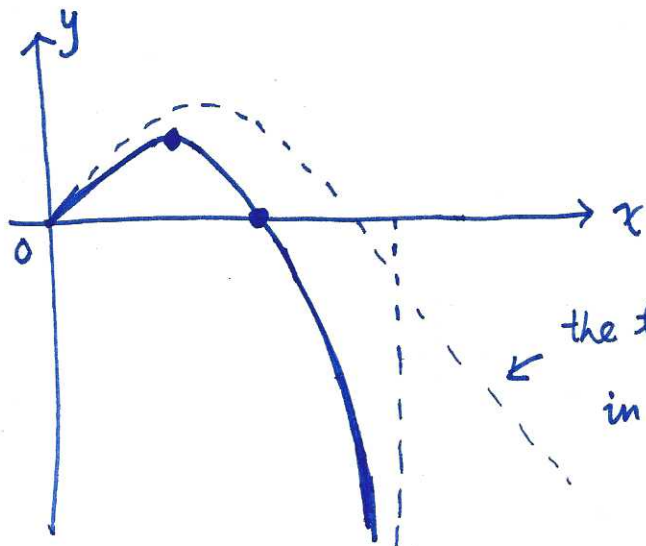


$$y = \frac{v(\infty)^2}{g} \ln \left[\cosh \frac{gt}{v(\infty)} \right] \approx \begin{cases} \frac{1}{2} gt^2 & t \ll \frac{v(\infty)}{g} \\ v(\infty)t & \text{at } t \gg \frac{v(\infty)}{g} \end{cases}$$

* Now we study the coupled x and y -motion

$$\begin{cases} \dot{v}_x = -\frac{c}{m} \sqrt{v_x^2 + v_y^2} v_x \\ \dot{v}_y = -g - \frac{c}{m} \sqrt{v_x^2 + v_y^2} v_y \end{cases}$$

it cannot be solved analytically. The textbook presents a numeric solution.



Remarks ① The highest height is lowered by the resistance compared to that in the vacuum.

② $v_y = 0$ occurs earlier, i.e. the highest point is reached earlier.

③ at $t \rightarrow \infty$, the trajectory becomes vertical, and $v_x(\infty) = 0$.

Then $v(\infty)$ is the same as in the vertical motion. Then

$$\dot{v}_x \approx -\frac{c}{m} v(\infty) v_x, \text{ then } v_x \approx A e^{-t/\tau}, \text{ with } \tau = \frac{m v(\infty)}{c}.$$

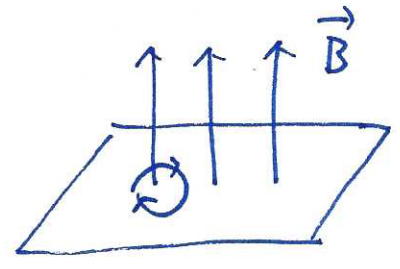
So $v_x \rightarrow 0$ exponentially. Thus $x(t) = \int_0^{\infty} v_x(t) dt$

converges, i.e. it can only travel for a finite distance along the x -direction.

§ Motion in a uniform magnetic field

$$\vec{F} = \frac{q}{c} \vec{v} \times \vec{B}$$

set $\vec{B} = B \hat{z}$



Gaussian Unit

$$\begin{cases} m \dot{v}_x = \frac{q}{c} B v_y \\ m \dot{v}_y = -\frac{q}{c} B v_x \\ m \dot{v}_z = 0 \end{cases}$$

$\rightarrow \omega = \frac{qB}{mc}$ cyclotron frequency

$$\Rightarrow \begin{cases} \dot{v}_x = \omega v_y \\ \dot{v}_y = -\omega v_x \end{cases}$$

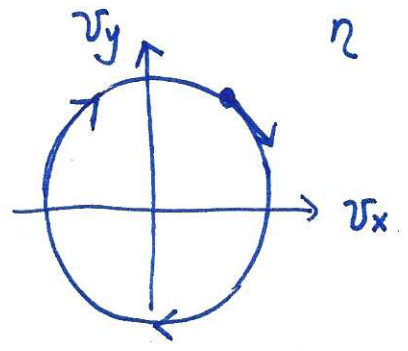
$$\Rightarrow v_x + i v_y = -i \omega (v_x + i v_y)$$

Define $\eta = v_x + i v_y$

$$\Rightarrow \boxed{\dot{\eta} = -i \omega \eta}$$

$$\Rightarrow \eta = A e^{-i \omega t}$$

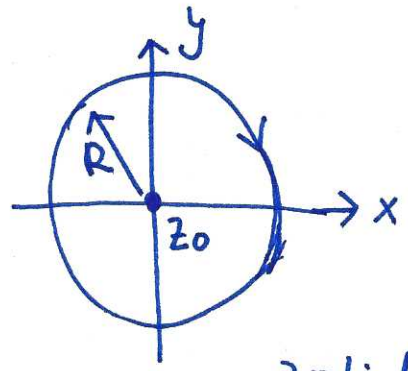
with $A = v_x(0) + i v_y(0)$



we also define $z = x + i y$

$$\Rightarrow z = \text{const} + \int \eta dt = z_0 + \frac{iA}{\omega} e^{-i \omega t}$$

center of the circle.



The cyclotron radius

$$R = \left| \frac{A}{\omega} \right| = \frac{v m c}{q B}$$

$$\Rightarrow \text{momentum magnitude } p = \frac{q B R}{c}$$

$$\rightarrow \text{orbital angular momentum } L = p R = \frac{q B R^2}{c}$$

Classically, the circular orbit can be at any size.

But quantum mechanically, it has a minimal size.

The orbital angular momentum $L_{\min} = \frac{qBR^2}{c} = \hbar$

$$\Rightarrow R = \sqrt{\frac{\hbar c}{qB}} \quad \leftarrow \text{the cyclotron radius.}$$