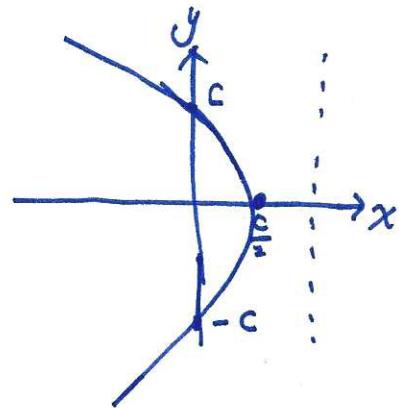


Lect 10 Kepler problem (II)

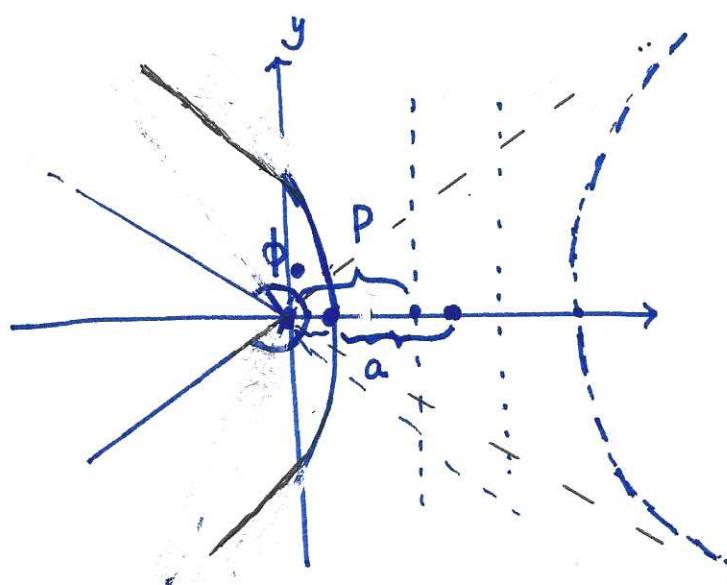
§ unbounded orbits : $r(\phi) = \frac{c}{1+e\cos\phi}$

$$\textcircled{1} e=1 \Rightarrow r(\phi=\pi) \rightarrow +\infty, \quad y^2 = -2c[x - \frac{c}{2}]$$



\textcircled{2} $e > 1$:

$$\frac{\left(x - \frac{ec}{e^2-1}\right)^2}{\left(\frac{c}{e^2-1}\right)^2} - \frac{y^2}{\left(\frac{c}{\sqrt{e^2-1}}\right)^2} = 1$$



$$P = \frac{c}{e}$$

$$\text{perihelion } \frac{c}{1+e}$$

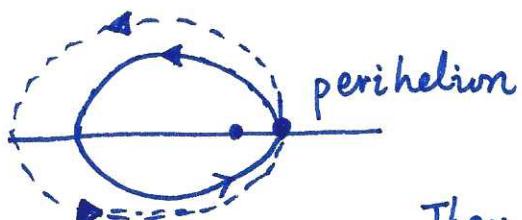
$$a = \frac{c}{e^2-1}$$

$$\text{center } \left[\frac{ec}{e^2-1}, 0 \right]$$

define $\phi_0 = \cos^{-1} \frac{1}{e} \Rightarrow r \text{ is finite when}$

$$-(\pi - \cos^{-1} \frac{1}{e}) < \phi < \pi - \cos^{-1} \frac{1}{e}$$

§ Change orbit



They tangent at the perigee \Rightarrow
are

$$\frac{C_1}{1+e_1} = \frac{C_2}{1+e_2}$$

$$e_2 = \lambda e_1$$

$$\text{Since } C = \frac{e^2}{\mu r}$$

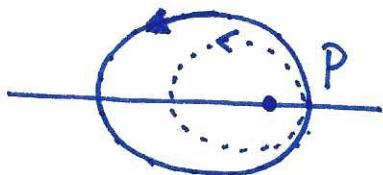
$$\Rightarrow C_2 = \lambda^2 C_1 \quad \Rightarrow \quad \frac{1+e_2}{1+e_1} = \frac{C_2}{C_1} = \lambda^2$$

$$\text{or } e_2 = \lambda^2 e_1 + (\lambda^2 - 1)$$

① If $\lambda > 1$, then $e_2 > e_1$. The two orbits have the same perigee
the orbit becomes larger and more elliptical. At $e_2 \geq 1$, the orbit
becomes open \rightarrow parabola and hyperbola.

② If $\lambda < 1$, then $e_2 < e_1$. Then the new orbit becomes smaller
and less elliptical. At $e_2 = 0$, the orbit becomes circular.

how about when $e_2 < 0$, then the equation



$$\text{of orbit changes to } r(\phi) = \frac{1}{1 - e_2 \cos \phi}$$

Then the perigee and apogee switch.

change from an elliptic orbit with (C_1, e_1) to another one with (C_2, e_2) .

Define the thrust factor $\frac{v_2}{v_1} = \lambda$

$$\begin{cases} \lambda > 1 & \text{forward thrust} \\ 1 > \lambda > 0 & \text{backward thrust} \end{cases}$$

Changing between circular orbits.

The eccentricity of the orbit is

$$e_1 = 0, \text{ and } C_1 = R_1$$

The eccentricity of the orbit 2 is e_2

$$\left\{ \begin{array}{l} r = \frac{C_2}{1 + e_2 \cos \phi} \\ C_2 = \lambda^2 R_1 \end{array} \right. \Rightarrow \frac{C_2}{1 + e_2} = \frac{\lambda^2 R_1}{1 + e_2} = R_1 \Rightarrow e_2 = \lambda^2 - 1$$

$$\text{and the apogee } \frac{C_2}{1 - e_2} = R_3 \Rightarrow C_2 = R_3(1 - e_2)$$

$$\lambda^2 R_1 = R_3(2 - \lambda^2) \Rightarrow \boxed{\lambda^2 = \frac{2R_3}{R_1 + R_3}} \text{ or } \lambda = \sqrt{\frac{2R_3}{R_1 + R_3}}$$

$$\text{The 2nd thrust. } \rightarrow \left\{ \begin{array}{l} r = C_3 = R_3 \\ e_3 = 0 \end{array} \right. \quad C_3 = \lambda'^2 C_2$$

$$\Rightarrow \lambda'^2 = \frac{C_3}{C_2} = \frac{R_3}{\lambda^2 R_1} = \frac{R_1 + R_3}{2R_1} \quad \text{or} \quad \lambda' = \sqrt{\frac{R_1 + R_3}{2R_1}}$$

The final speed and the initial speed

$$\left\{ \begin{array}{l} v_3 = v_{2,\text{app}} \lambda' \\ \lambda v_1 = v_{2,\text{peri}} \end{array} \right. \text{ and } v_{2,\text{app}} \cdot R_3 = v_{2,\text{peri}} R_1$$

$$\Rightarrow v_3 = \lambda' \frac{v_{2,\text{app}}}{v_{2,\text{peri}}} \cdot \lambda v_1 = \lambda' \lambda \frac{R_1}{R_3} v_1 = \sqrt{\frac{R_1}{R_3}} v_1$$

