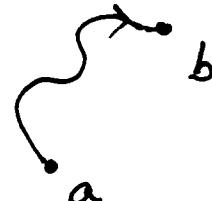


Lect 4 fundamental theorems of vector calculus

E: fundamental theorems : integral of a total derivative
is determined by the boundary

① Calculus $\int_a^b \frac{df}{dx} dx = f(b) - f(a)$ — 1D \vec{r}



② Curved line $dT = \nabla T \cdot d\vec{r}$

$$\underbrace{\int_{\vec{a}}^{\vec{b}} (\nabla T) \cdot d\vec{r}}_{\text{line}} = \int_{T(\vec{a})}^{T(\vec{b})} dT = T(\vec{b}) - T(\vec{a})$$

boundary: two ends

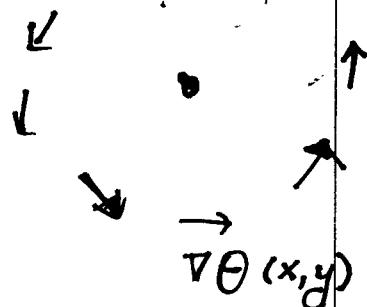
$\int_a^b \nabla T \cdot d\vec{r}$ is independent of the path from $a \rightarrow b$

$\boxed{\oint_a^b \nabla T \cdot d\vec{r} = 0}$ — Caveat: only valid for single valued function T .

* if T is a multi-valued function, say, $\Theta(x, y)$

the azimuthal angle of the point (x, y) , because Θ is only uniquely defined up to $2n\pi$, $\Rightarrow \boxed{\oint \nabla \Theta \cdot d\vec{r} = 2n\pi}$

in this class, unless explicitly mentioned,
we only consider single-valued function

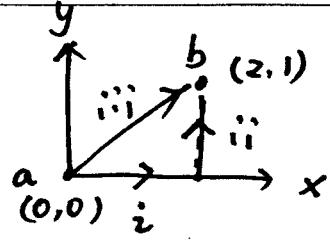


$$\nabla \Theta(x, y)$$

$$\text{Ex: } T = xy^2$$

$$\nabla T = y^2 \hat{x} + 2xy \hat{y}$$

$$d\vec{r} = dx \hat{x} + dy \hat{y} + dz \hat{z}$$



following $i+ii \Rightarrow$

$$\int_i \nabla T \cdot d\vec{r} + \int_{ii} \nabla T \cdot d\vec{r}$$

$$= \int_i y^2 dx + \int_{ii} 2xy dy = 0 + 4 \int_0^1 y dy = 2$$

$$\text{following } iii \quad y = \frac{x}{2} \Rightarrow \int_{iii} \nabla T \cdot d\vec{r} = \int_{iii} y^2 dx + 2xy dy$$

$$= \int_0^2 \frac{x^2}{4} dx + \frac{x^2}{2} dx = \left(\frac{1}{12} x^3 + \frac{x^3}{3} \right) \Big|_0^2 = \frac{8}{4} = 2$$

for both cases

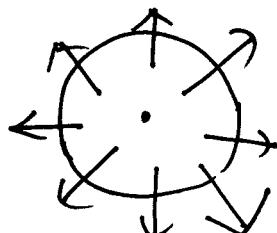
$$\boxed{\int \nabla T \cdot d\vec{r} = T(2,1) - T(0,0) = 2}$$

§ fundamental theorem of divergence — Gauss's theorem

$$\oint_V (\nabla \cdot \vec{v}) dv = \oint_S \vec{v} \cdot d\vec{a}$$

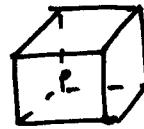
\int facets within the volume = flow out through the surface.

boundary



explanation: let's consider a small cube

with center (x, y, z) and edge length Δa



then the flux pass the surface:

$$\text{up \& down } \left(V_z(x, y, z + \frac{\Delta a}{2}) - V_z(x, y, z - \frac{\Delta a}{2}) \right) (\Delta a)^2 \\ = \partial_z V_z (\Delta a)^3$$

$$\text{left \& right} + \text{front \& back} = \left[V_x(x + \frac{\Delta a}{2}, y, z) - V_x(x - \frac{\Delta a}{2}, y, z) \right] (\Delta a)^2 \\ + \left[V_y(x, y + \frac{\Delta a}{2}, z) - V_y(x, y - \frac{\Delta a}{2}, z) \right] (\Delta a)^2 \\ = (\partial_x V_x) (\Delta a)^3 + (\partial_y V_y) (\Delta a)^3$$

$$\Rightarrow \oint \vec{V} \cdot d\vec{a} = \nabla \cdot \vec{V} (\Delta a)^3 = \int_V (\nabla \cdot \vec{V}) dz.$$

for large volume, you can cut the system into small cubes,
a collection of
apply the above result, and add them together.

$$\sum \oint \vec{V} \cdot d\vec{a} = \oint \vec{V} \cdot d\vec{a}$$

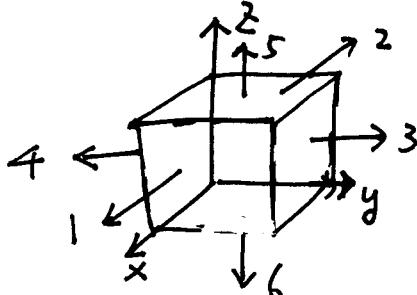
Ex: $\vec{V} = y^2 \hat{x} + (2xy + z^2) \hat{y} + (zyz) \hat{z}$

the external surface, all the contribution
sum of
on internal surfaces
cancel

and the cube.

Check Gauss's law.

$$\nabla \cdot \vec{V} = 2x + 2y$$



$$\int \nabla \cdot \vec{v} = \int dx dy dz \cdot 2(x+y) = 2 \int_0^1 dz \int_0^1 dx dy (x+y) = 4 \int_0^1 dz \int_0^1 dy \int_0^1 x dx = 2$$

- $$\bullet \text{ flux } \int_1 + \dots + \int_6 = \oint d\vec{r}$$

$$\int_1 + \int_2 = \int_0^1 dy dz y^2 - \int_0^1 dy dz y^2 = 0$$

$$\int_3 + \int_4 = \int_0^1 dx dz (2xy + z^2) - \int_0^1 dy dz (2xy + z^2) = z \int_0^1 dx dz x = 1$$

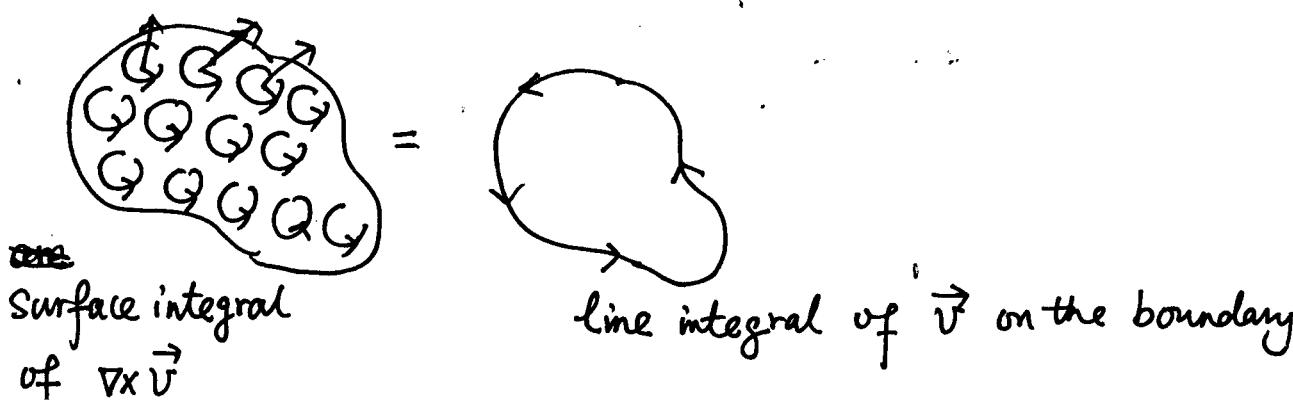
$$\int_5 + \int_6 = \int_0^1 \int_0^x dy dx (zyz) - \int_0^1 \int_x^1 dy dx (zyz) = \int_0^1 \int_0^x dy dx zy = 1$$

$$\Rightarrow S_1 + \dots + S_6 = 2$$

8 fundamental laws ofcurls — Stoke's theorem

$$\int_S (\nabla \times \vec{V}) \cdot d\vec{a} = \oint \vec{V} \cdot d\vec{l}$$


 A diagram illustrating the divergence theorem. It shows a closed surface with an upward-pointing arrow indicating the direction of the outward normal vector. Below the surface, the word "surface" is written. To the right of the surface, there is a closed loop representing the boundary, with the word "boundary" written below it.

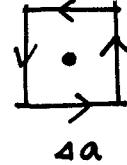


check for a planer version.

(5)

$$\int_S \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right) dx dy = \oint \vec{V} \cdot d\vec{l}$$

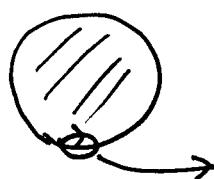
$$\begin{aligned}\oint \vec{V} \cdot d\vec{l} &= \left\{ -V_y(x - \frac{\Delta a}{2}, y) + V_y(x + \frac{\Delta a}{2}, y) \right. \\ &\quad \left. + V_x(x, y - \frac{\Delta a}{2}) - V_x(x, y + \frac{\Delta a}{2}) \right\} \Delta a \\ &= \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right) (\Delta a)^2.\end{aligned}$$



→ $\int (\nabla \times \vec{V}) \cdot d\vec{a}$ only depend on boundary, but not the surface. • A closed curve in 3D, doesn't uniquely determine a surface. All the surfaces share the same boundary yield the same result.

for a closed surface

$$\oint (\nabla \times \vec{V}) \cdot d\vec{a} = \oint \vec{V} \cdot d\vec{l} = 0$$



contract the boundary
curve to a point

$$\oint (\nabla \times \vec{V}) \cdot d\vec{a} = \int \nabla \cdot (\nabla \times \vec{V}) dz = 0$$

$$\text{Ex } \vec{v} = (2xz + 3y^2) \hat{y} + 4yz^2 \hat{z},$$

square surface

$$\nabla \times \vec{v} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \hat{x} + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{y}$$

$$+ \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{z} = (4z^2 - 2x) \hat{x} + 2z \hat{z}$$

$$\int \nabla \times \vec{v} \cdot d\vec{a} = \int_{x=0}^{(4z^2 - 2x)} dy dz = 4 \int_0^1 dy \int_0^1 z^2 dz = \frac{4}{3}$$

$$x=z=0$$

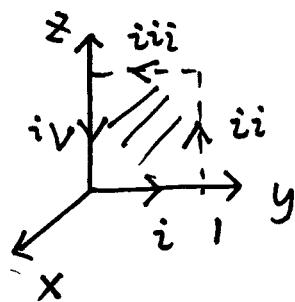
$$\oint \vec{v} \cdot d\vec{l} = S_i + \dots + S_{iv} \Rightarrow S_i + S_{iii} = \int_i^l dy (2xz + 3y^2) - \int_{iii}^l dy (2xz + 3y^2) \Big|_{x=z=0}$$

$$= \int_0^1 dy (3y^2 - 3y^2) = 0$$

$$S_{ii} + S_{iv} = \int_0^1 dz 4yz^2 - \int_0^1 dz 4yz^2 = 4 \int_0^1 dz z^2 = \frac{4}{3}$$

$$\begin{matrix} \rightarrow & \uparrow \\ x=0, y=1 & x=0, y=0 \end{matrix}$$

$$\Rightarrow \oint \vec{v} \cdot d\vec{l} = \frac{4}{3} = \oint \nabla \times \vec{v} \cdot d\vec{a}$$



integral by parts

$$\nabla \cdot (f \vec{A}) = f(\nabla \cdot \vec{A}) + \vec{A} \cdot (\nabla f)$$

$$\Rightarrow \int_V f(\nabla \cdot \vec{A}) dV = \int_V [\nabla \cdot (f \vec{A}) - \vec{A} \cdot (\nabla f)] dV$$

$$= \oint f \vec{A} \cdot d\vec{a} - \int_V \vec{A} \cdot \nabla f dV$$



in some situations, we can take the surface to infinity.

- if $f \cdot \vec{A}$ decays very quickly, the surface integral often vanishes!