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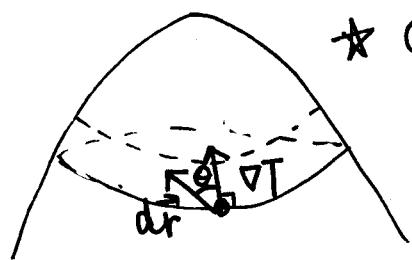
Lect 2 Differential calculus

§ gradient:

Consider a scalar function $T(x, y, z)$.

$$\begin{aligned} dT(x, y, z) &= \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz \\ &= \left(\frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z} \right) \cdot (dx \hat{x} + dy \hat{y} + dz \hat{z}) \\ &= \nabla T \cdot d\vec{r}, \text{ where } \nabla T = \frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z} \end{aligned}$$

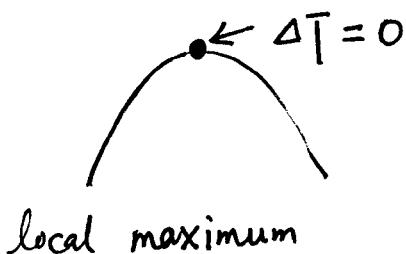
$\Rightarrow dT = |\nabla T| \cdot |d\vec{r}| \cos\theta$, where θ is the angle between ∇T and $d\vec{r}$.



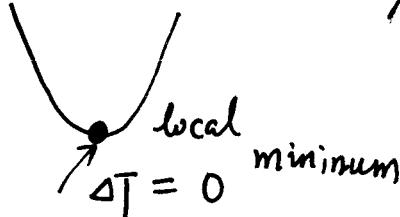
* Climb a hill. The direction of ∇h $h(x, y, z)$ is the steepest direction.

The magnitude of ∇h is the slope along this hardest direction.

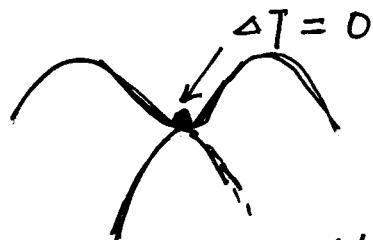
• Stationary point: $\nabla T = 0$. $dT \propto O(\Delta r)^2$



local maximum



local minimum



Saddle point
maximum along one direct
minimum along another dire

$$\text{Ex: } r = \sqrt{x^2 + y^2 + z^2}$$

$$\nabla r = \frac{\partial r}{\partial x} \hat{x} + \frac{\partial r}{\partial y} \hat{y} + \frac{\partial r}{\partial z} \hat{z} = \frac{1}{\sqrt{x^2 + y^2 + z^2}} (x \hat{x} + y \hat{y} + z \hat{z})$$

$$= \frac{\vec{r}}{r} = \hat{r}$$

→ nabla operator: $\nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$ (vector operator)

The effect of ∇ is: for any scalar function $f(x, y, z)$

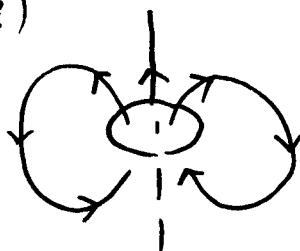
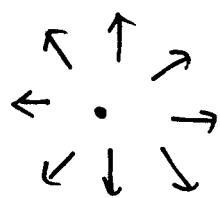
$$\nabla f = \hat{x} \frac{\partial f}{\partial x} + \hat{y} \frac{\partial f}{\partial y} + \hat{z} \frac{\partial f}{\partial z}$$

& divergence: — applying the ∇ -operator on a vector function: the point product

for a vector field $\vec{v} = v_x(x, y, z) \hat{x}$ each component
 $+ v_y(x, y, z) \hat{y}$ is a function
 $+ v_z(x, y, z) \hat{z}$ of (x, y, z)

Example: ① electric field $\vec{E}(x, y, z) = [E_x(x, y, z), E_y(x, y, z), E_z(x, y, z)]$

$$\textcircled{2} \quad \vec{B}(x, y, z)$$

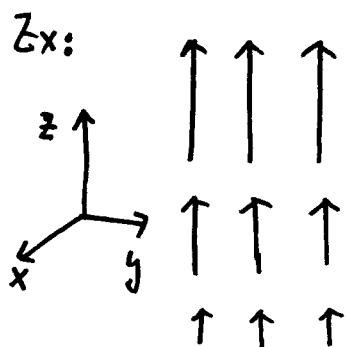


divergence $\nabla \cdot \vec{v} = (\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}) (v_x \hat{x} + v_y \hat{y} + v_z \hat{z})$

 $= \frac{\partial}{\partial x} v_x + \frac{\partial}{\partial y} v_y + \frac{\partial}{\partial z} v_z$

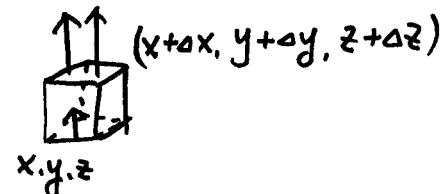
* a scalar function has no divergence.

* Physical meaning: $\nabla \cdot \vec{v}$ is a measure of the vector \vec{v} spreads out from a point ~~or~~.



$\vec{v} = (0, 0, v_z(z))$

$\nabla \cdot \vec{v} = \frac{\partial}{\partial z} v_z > 0.$



Consider a small box:

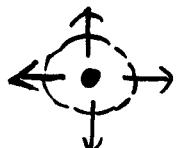
The flux of \vec{v} to outside
net

 $v_z(z+\Delta z) \Delta y \Delta x - v_z(z) \Delta y \Delta x$

$= \frac{\partial}{\partial z} v_z \Delta x \Delta y \Delta z$

$= \nabla \cdot \vec{v} (\Delta x \Delta y \Delta z)$

or Ex



$\vec{v} = (x, y, z) = \vec{r}$

Consider a small sphere with Δr

the flux goes outside $4\pi(\epsilon r)^2 \cdot \Delta r = 4\pi (\Delta r)^3$

$= \frac{4}{3}\pi (\epsilon r)^3 \cdot (\nabla \cdot \vec{r})$

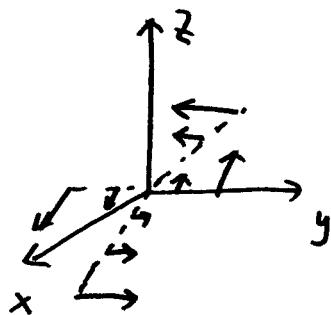
$= \Delta V (\nabla \cdot \vec{v})$

§3. Circulation

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix} = \hat{x} \left(\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \right) + \hat{y} \left(\frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x} \right) + \hat{z} \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right)$$

$\therefore \nabla \times \vec{V}$ is a measure of how much \vec{V} "curls around" the point.

The direction of $\nabla \times \vec{V}$ is perpendicular to the circulation plane

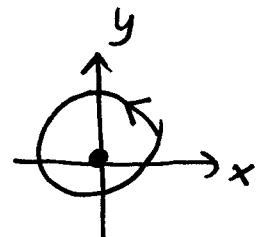


$$\text{Ex: } \vec{V} = (-y, x, 0)$$

Circulation around a circle

of radial Δr , along the ~~outward~~ counter-clockwise

$$\Delta r \cdot 2\pi \Delta r = \pi(\Delta r)^2 \cdot 2$$



direction

$$\nabla \times \vec{V} = \hat{z} \cdot 2$$

$$\Rightarrow \text{circulation} = \Delta S \hat{z} \cdot (\nabla \times \vec{V})$$

④ Product rules

$$\left\{ \begin{array}{l} \nabla(f+g) = \nabla f + \nabla g \\ \nabla \cdot (\vec{A} + \vec{B}) = \nabla \cdot \vec{A} + \nabla \cdot \vec{B} \\ \nabla \times (\vec{A} + \vec{B}) = \nabla \times \vec{A} + \nabla \times \vec{B} \end{array} \right.$$

$$\begin{aligned} \nabla(kf) &= k \nabla f \\ \nabla \cdot (k\vec{A}) &= k \nabla \cdot \vec{A} \\ \nabla \times (k\vec{A}) &= k \nabla \times \vec{A} \end{aligned}$$

k is a const

linear operator
properties of

more $\nabla(fg) = f \nabla g + \nabla f g$

$$\nabla(f/g) = \frac{1}{g} \nabla f - \frac{f \nabla g}{g^2}$$

$$\nabla \cdot (f \vec{A}) = f(\nabla \cdot \vec{A}) + \vec{A} \cdot \nabla f$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})$$

Note
required
to
remember

$$\nabla \times (f \vec{A}) = f(\nabla \times \vec{A}) - \vec{A} \times (\nabla f)$$

$$\nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - (\vec{A} \cdot \nabla) \vec{B} + \vec{A} (\nabla \cdot \vec{B}) - \vec{B} (\nabla \cdot \vec{A})$$

\therefore Laplacian : divergence of ~~the~~ gradient

$$\begin{aligned}\nabla \cdot (\nabla T) &= \frac{\partial}{\partial x} (\nabla T)_x + \frac{\partial}{\partial y} (\nabla T)_y + \frac{\partial}{\partial z} (\nabla T)_z \\ &= \frac{\partial^2}{\partial x^2} T + \frac{\partial^2}{\partial y^2} T + \frac{\partial^2}{\partial z^2} T = \nabla^2 T\end{aligned}$$

- Curl of gradient is zero

$$\nabla \times (\nabla T) = 0 \quad \rightarrow$$

$$[\nabla \times (\nabla T)]_z = \frac{\partial}{\partial x} (\nabla T)_y - \frac{\partial}{\partial y} (\nabla T)_x = \left(\frac{\partial^2}{\partial x \partial y} - \frac{\partial^2}{\partial y \partial x} \right) T = 0$$

similarly $[\nabla \times (\nabla T)]_x = [\nabla \times (\nabla T)]_y = 0$.

- Divergence of a curl is zero

$$\nabla \cdot (\nabla \times \vec{v}) = 0$$

$$\begin{aligned}\nabla \cdot (\nabla \times \vec{v}) &= \frac{\partial}{\partial x} [\nabla \times \vec{v}]_x + \frac{\partial}{\partial y} [\nabla \times \vec{v}]_y + \frac{\partial}{\partial z} [\nabla \times \vec{v}]_z \\ &= \frac{\partial}{\partial x} \left[\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right] + \frac{\partial}{\partial y} \left[\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right] + \frac{\partial}{\partial z} \left[\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right] \\ &= \left(\frac{\partial^2}{\partial x \partial y} - \frac{\partial^2}{\partial y \partial x} \right) v_z + \left(\frac{\partial^2}{\partial z \partial x} - \frac{\partial^2}{\partial x \partial z} \right) v_y + \left(\frac{\partial^2}{\partial y \partial z} - \frac{\partial^2}{\partial z \partial y} \right) v_x \\ &= 0\end{aligned}$$

(7)

- Curl of Curl

$$\nabla \times (\nabla \times \vec{U}) = \nabla(\nabla \cdot \vec{U}) - \nabla^2 \vec{U} \leftarrow \begin{matrix} \text{leave as} \\ \text{an exercise} \end{matrix}$$

definition of $\nabla^2 U^2 = (\nabla^2 U_x, \nabla^2 U_y, \nabla^2 U_z)$